



Typing and Exceptions for Algorithmic Skeletons

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Agenda

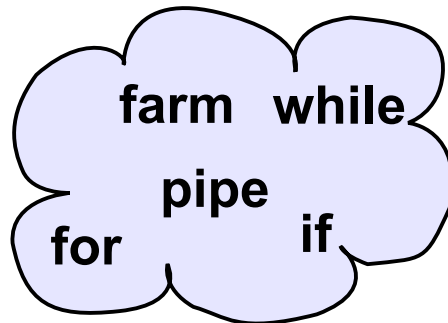
- **Introduction to Algorithmic Skeletons**
- Our Skeletons and Libraries
- Typing Skeletons
- Exceptions
- Semantics for Skeletons and Exceptions
- Conclusion and Future Work

What are Algorithmic Skeletons?

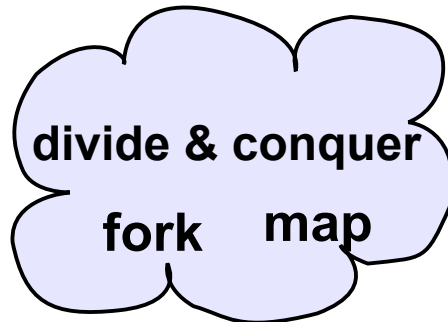
- **High Level** Programming Model [Cole89]
- Hides the complexity of parallel/distributed programming
- Exploits **nestable** parallelism **patterns**

Parallelism Patterns

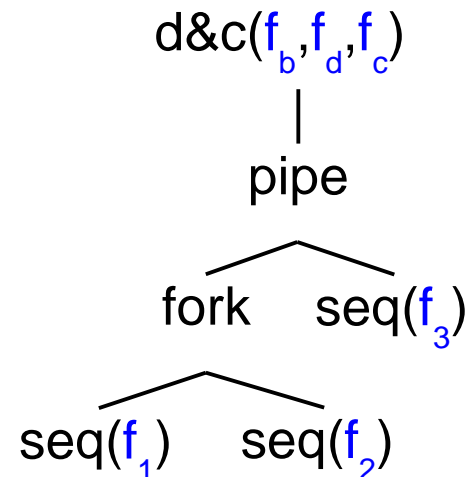
Task



Data



BLAST Skeleton Program



What are Algorithmic Skeletons?

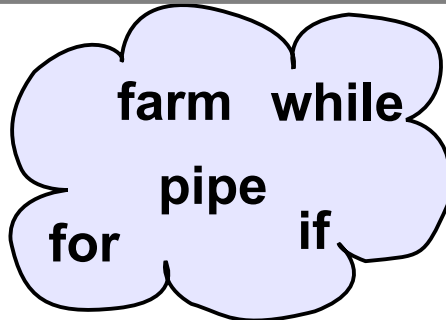
```
public boolean condition(BlastParams param)
{
    File file = param.dbFile;

    return file.length() > param.maxDBSize;
}
```

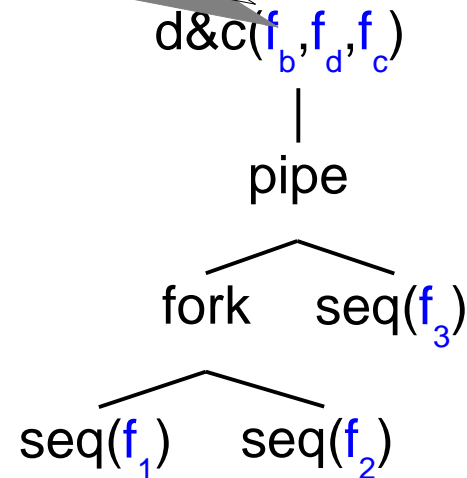
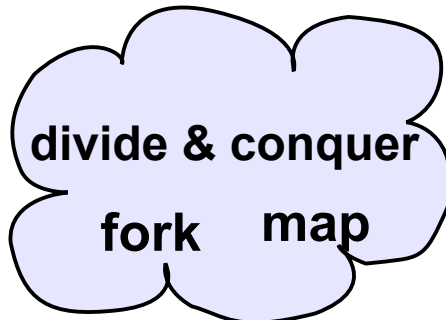
Programming

Skeleton Program

Task

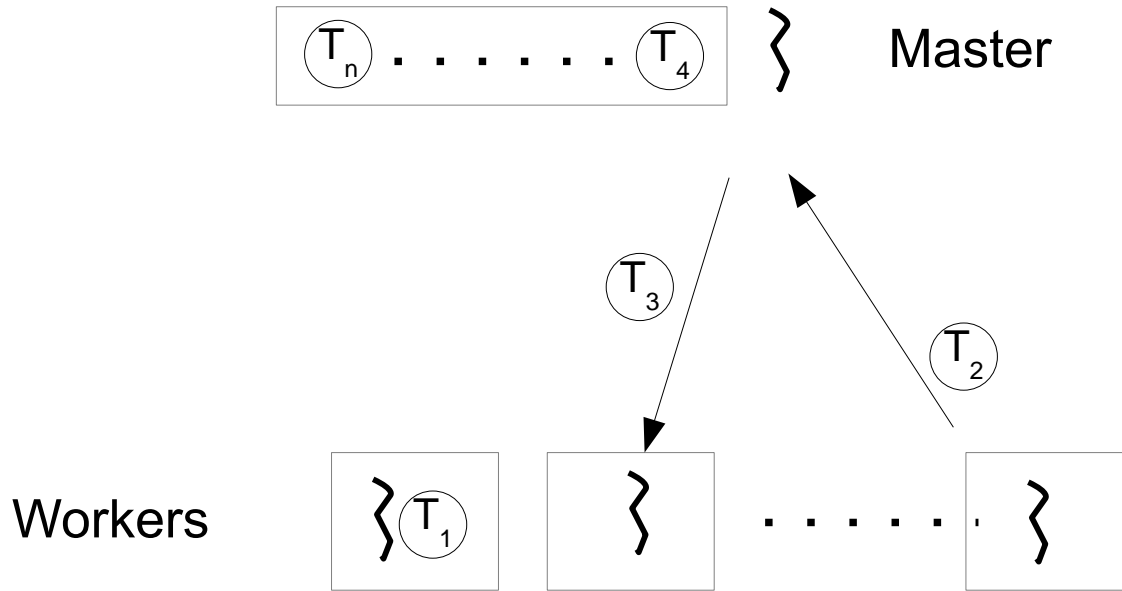


Data



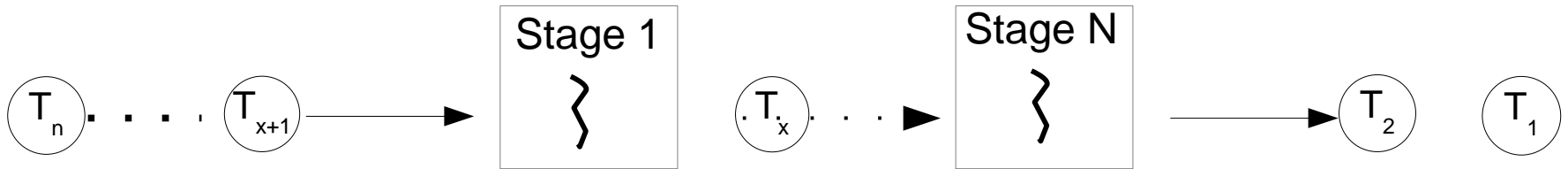
The Farm

(a.k.a. Master-Slave)



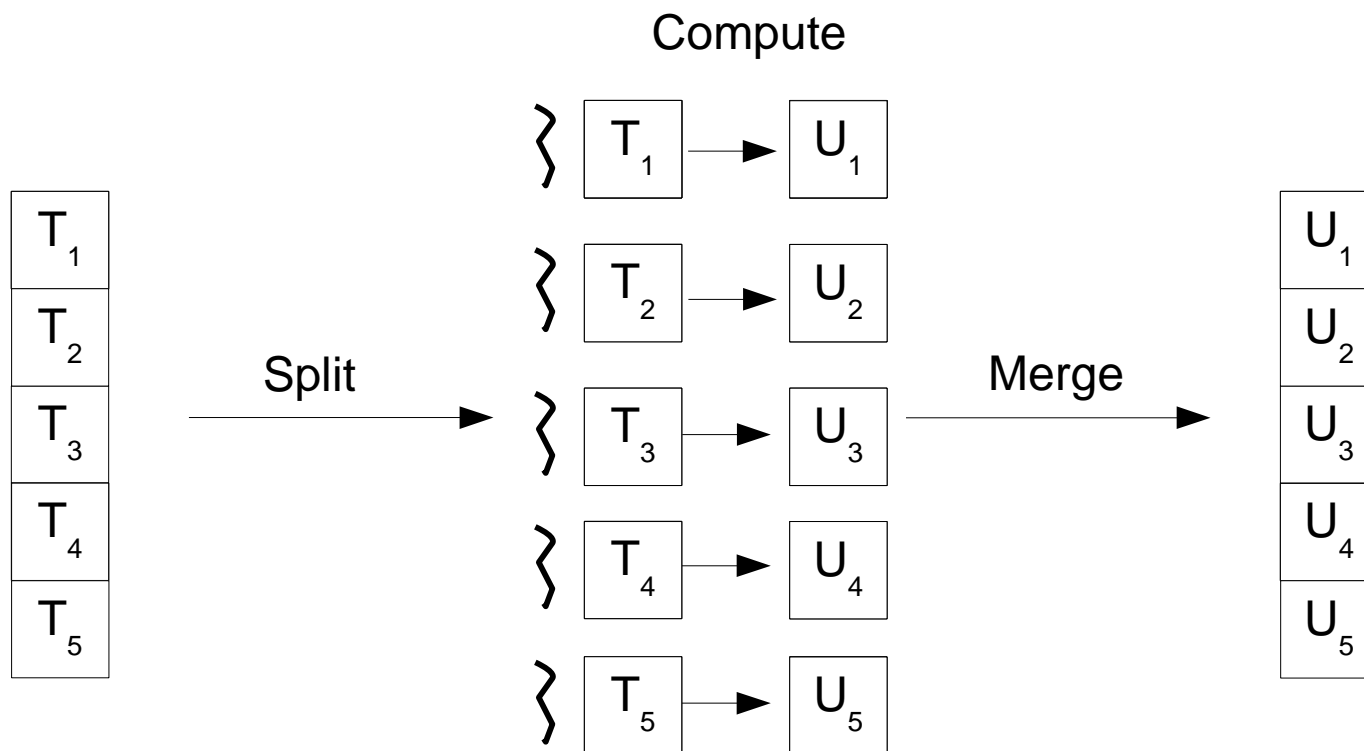
- **The** skeleton for embarrassingly parallel applications.
- Features: dispatching, load balancing, fault tolerance
- Note that each **worker** can be another skeleton

The Pipe



- Use cases:
 - Image manipulation
 - Preliminary preparation
- Note that each **stage** can be another skeleton

The Map



- Note that the **split**, **compute** and **merge** may be other skeletons

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Skandium Library / Calcium Library

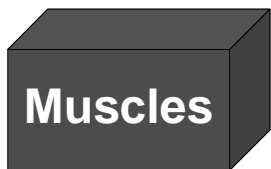
<http://skandium.niclabs.cl>

<http://proactive.objectweb.org>

- Java library, Open Source
- Nestable Task and Data parallel Skeletons
- Type Safe Skeleton API
- Multi-core parallelism in Skandium / Distribution in Calcium (Active Objects)
- Exception management in Skandium
- Examples Bundle:
 - QuickSort, NQueens, Pi Decimals.

Our Algorithmic skeletons

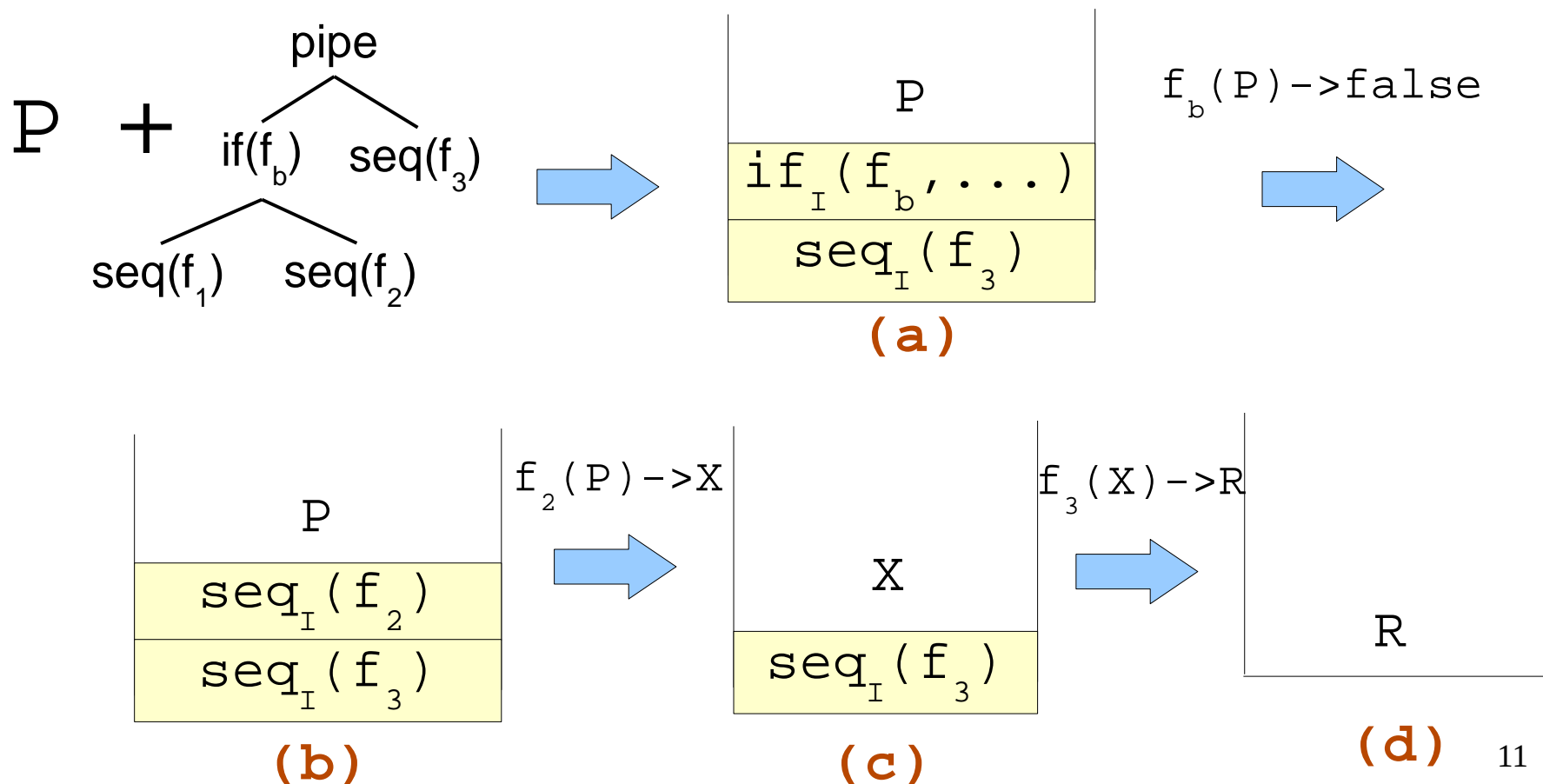
$\Delta ::= \text{seq}(f_e) \mid \text{farm}(\Delta) \mid \text{pipe}(\Delta_1, \Delta_2)$
 $\text{while}(f_c, \Delta) \mid \text{for}(i, \Delta) \mid \text{if}(f_c, \Delta_{\text{true}}, \Delta_{\text{false}})$
 $\text{map}(f_s, \Delta, f_m) \mid \text{fork}(f_s, \{\Delta_i\}, f_m) \mid \text{d\&c}(f_s, f_c, \Delta, f_m)$



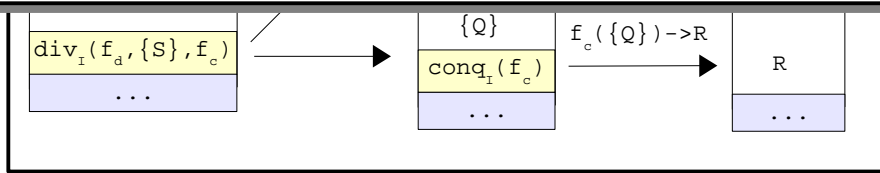
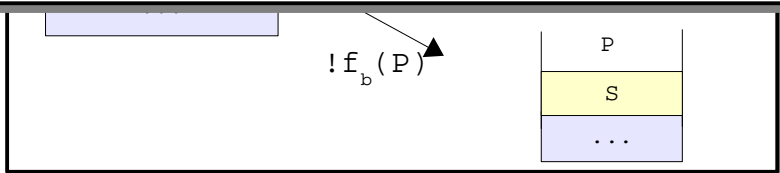
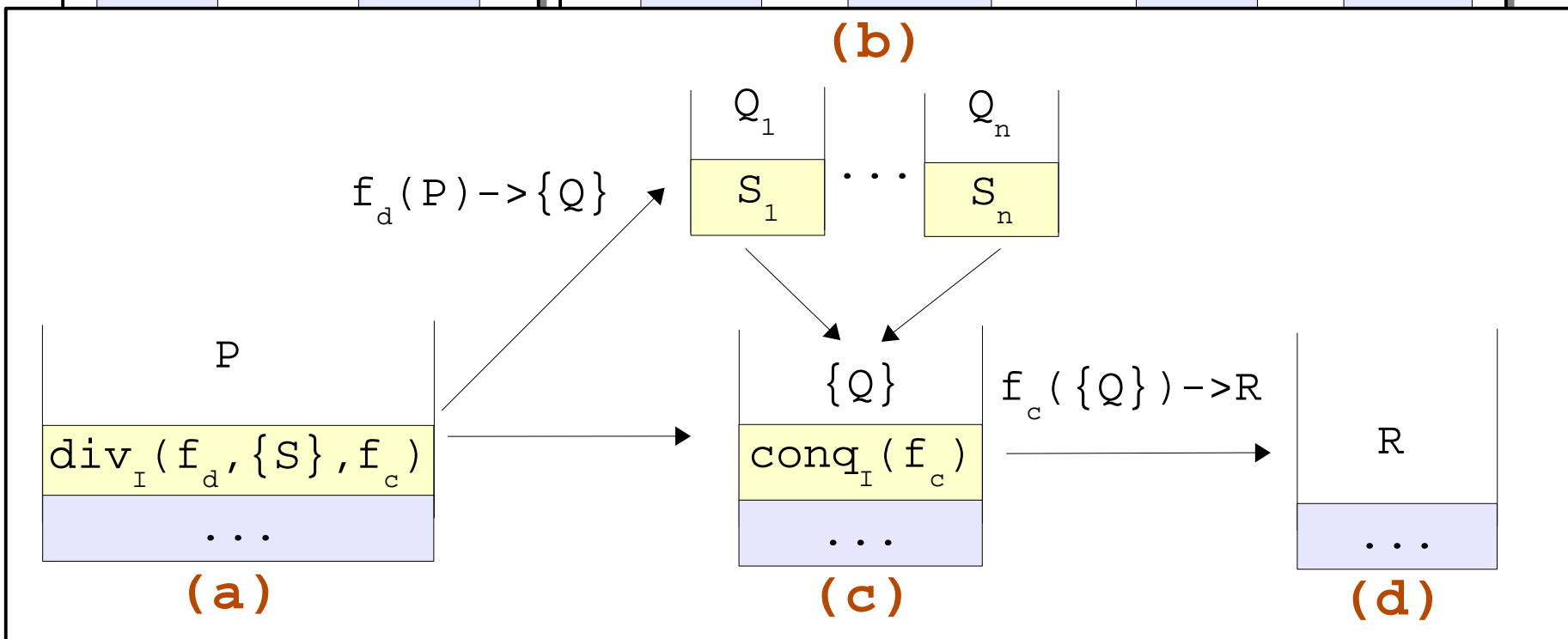
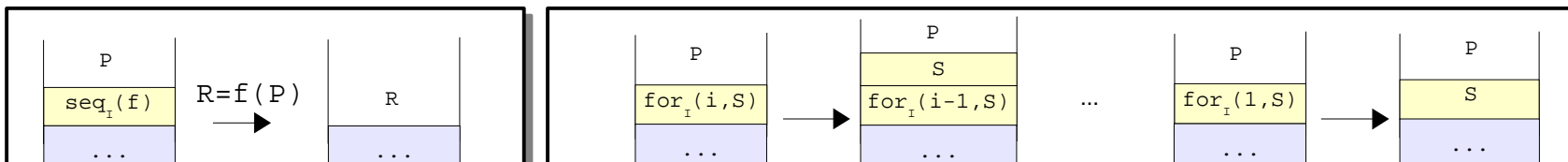
	Input		Output	Description
f_e	1		1	Execute
f_s	1		N	Split
f_m	N		1	Merge
f_c	1		boolean	Condition

Executing Skeletons

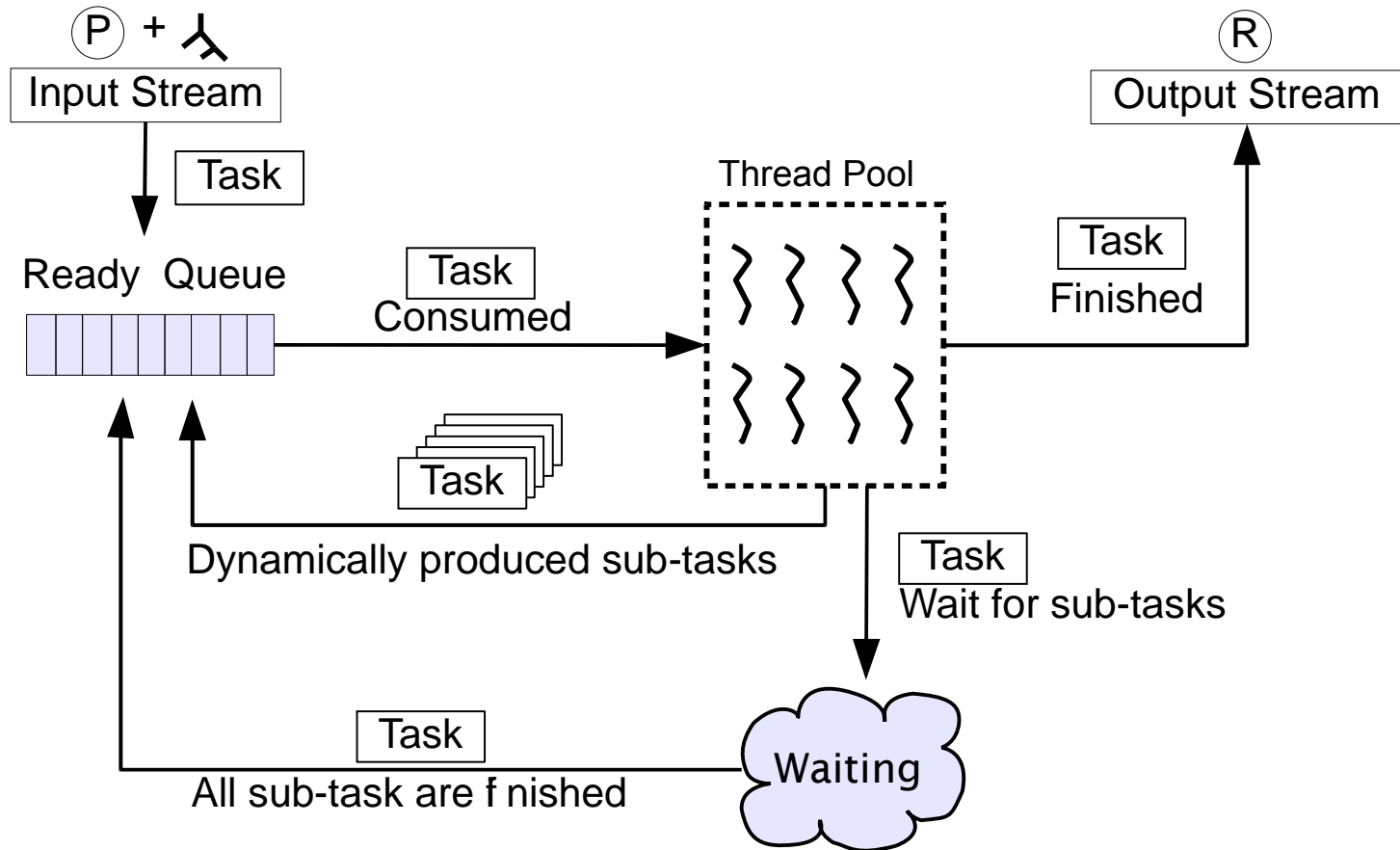
Skeletons have a lower level representation: **instructions**



Skeleton semantics



Skandium in a Nutshell



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Typing Skeletons

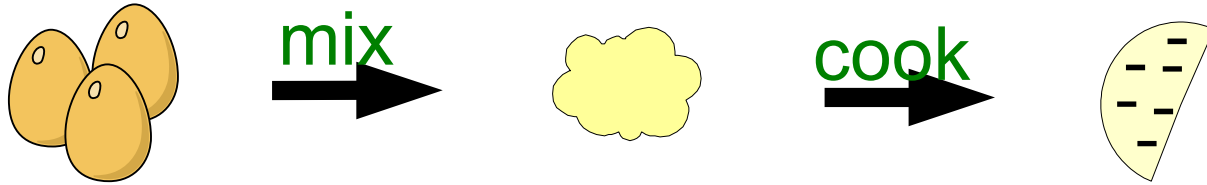
Formalisation



- Formal Type System for nestable Skeletons
- Proved Subject Reduction property
- Formalises type transfer between muscles

Implementation

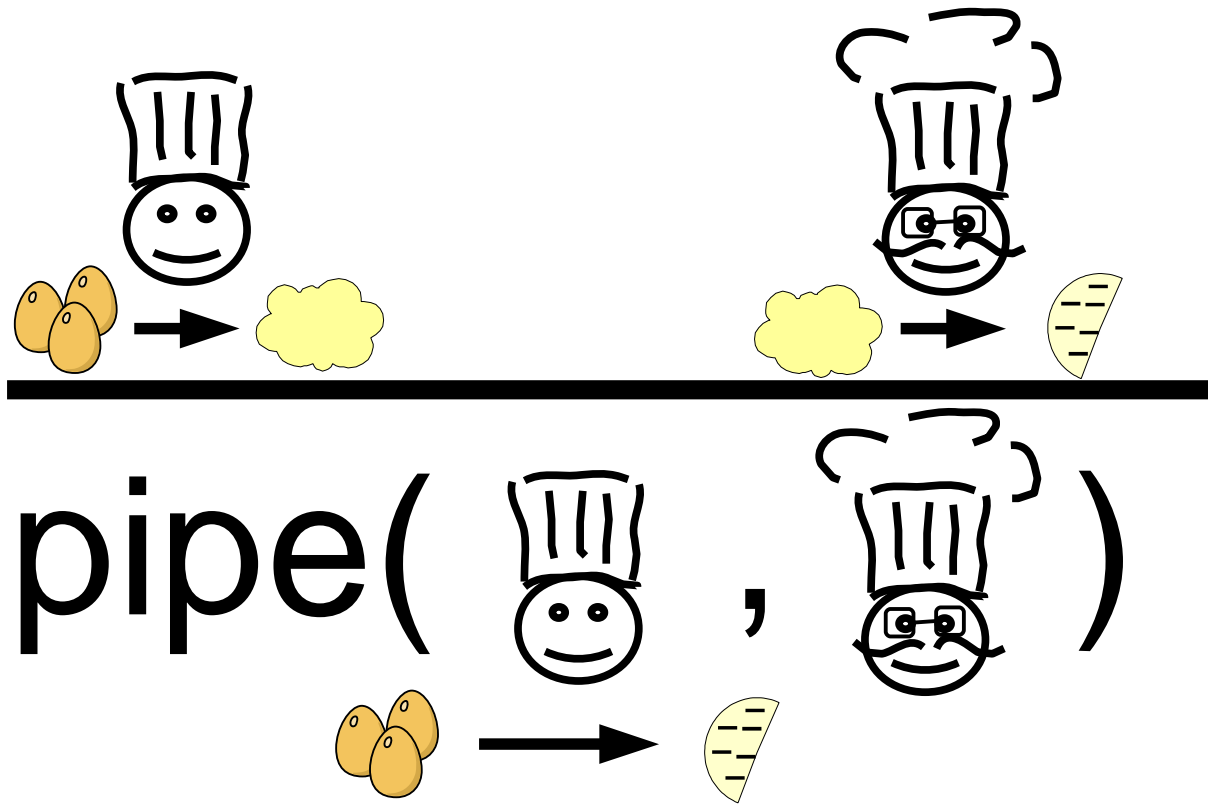
- Implemented Type System in Java
- Take advantage of Generics
- No further type casts inside muscles
- Type errors detected at skeleton composition

An Omelette Pipe



pipe( , )

Omelette Pipe: Type Rule



Do we need to check that the input of the chef is mixed eggs?

Type System

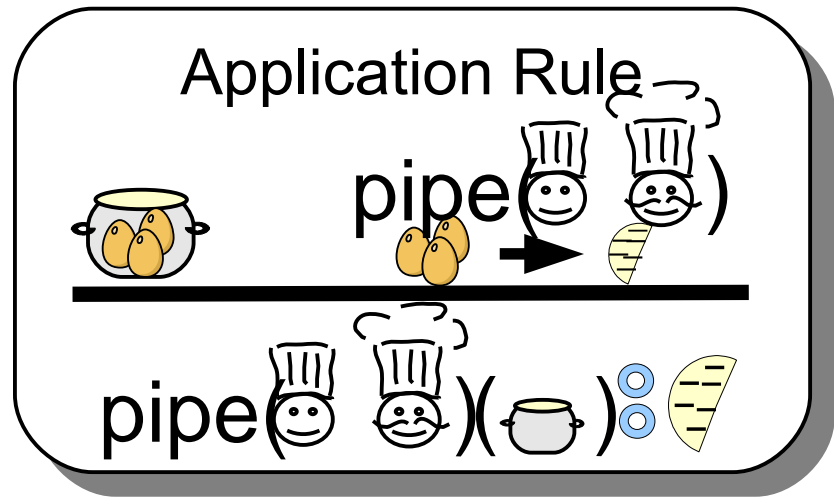
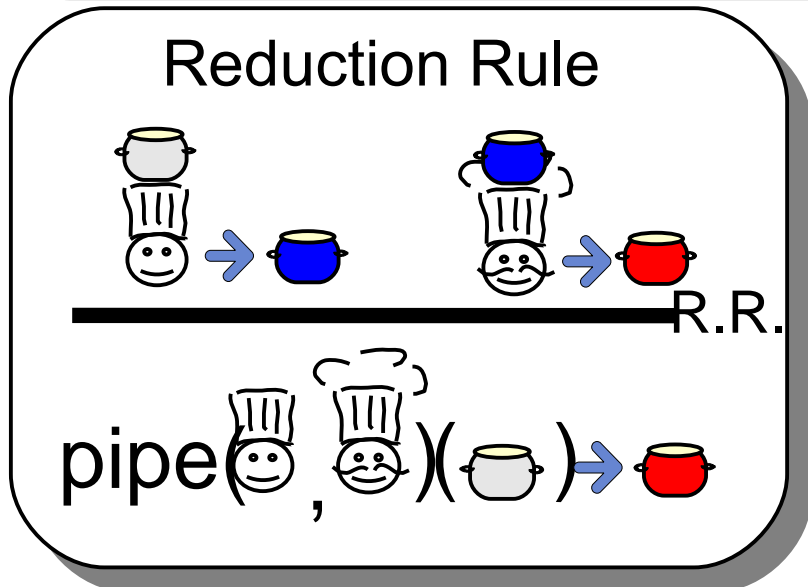
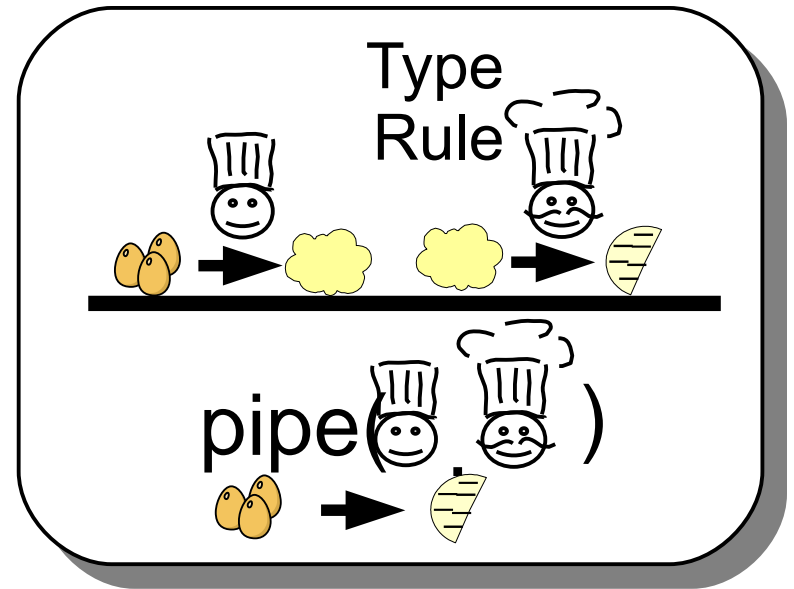
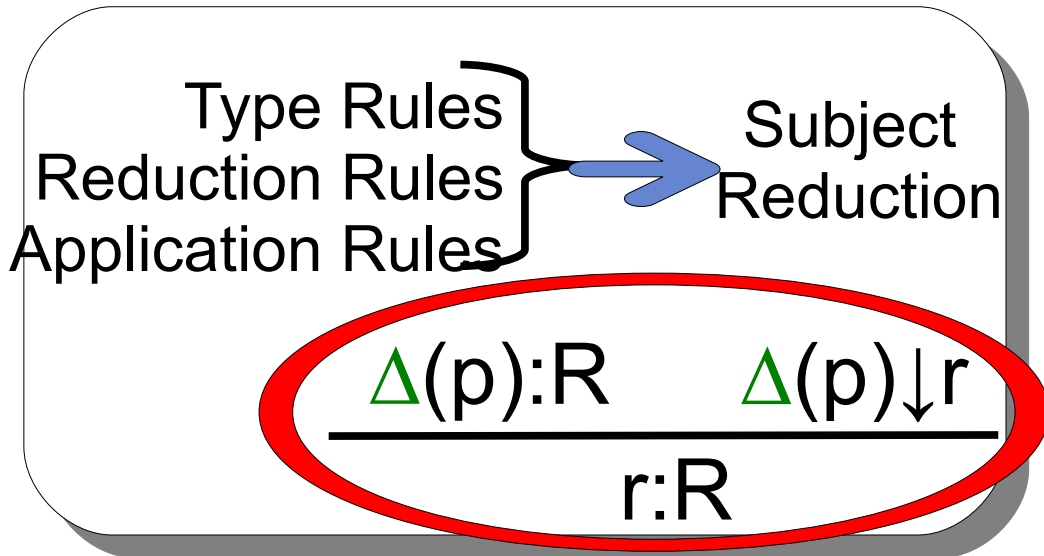
- Typing pipe

$$\frac{\Delta_1 : P \rightarrow X \quad \Delta_2 : X \rightarrow R}{\text{pipe}(\Delta_1, \Delta_2) : P \rightarrow R}$$

- Typing divide and conquer

$$\frac{f_d : P \rightarrow \{P\} \quad f_b : P \rightarrow \text{boolean} \quad \Delta : P \rightarrow R \quad f_c : \{R\} \rightarrow R}{\text{d\&c}(f_d, f_b, \Delta, f_c) : P \rightarrow R}$$

Manual check?



From Theory to Practice

- Use Java Generics to enforce type system
- No type validation to be implemented
- Same types for Java and skeletons

Pipe Type Rule

$$\frac{\Delta_1 : P \rightarrow X \quad \Delta_2 : X \rightarrow R}{\text{pipe}(\Delta_1, \Delta_2) : P \rightarrow R}$$


```
<X> Pipe<P,R>(
  Skeleton<P,X> stage1,
  Skeleton<X,R> stage2){...}
```

```
Class Pipe<P,R>{...}
```

Type Safe Muscles

```
class Chef implements Execute{
```

```
    public Object exec(Object input){
```

```
        Mix mix = (Mix) input;
```

```
        ...
```

```
        return output;
```

```
    }
```

```
        throw new ClassCastException()
```



Manual check

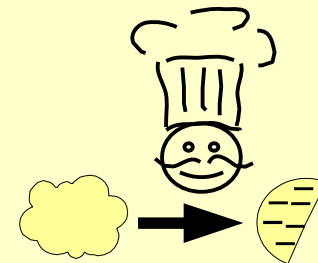
```
class Chef implements Execute<Mix, Omelette>{
```

```
    public Omelette exec(Mix input){
```

```
        ...
```

```
        return output;
```

```
    }
```



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Exceptions in Skandium

- Premise: **All user provided code may, at some point, generate exceptions.** Such as:
 - File open, access errors
 - Code errors, such as index out of bounds
 - etc..
- Algorithmic Skeletons need to address this reality.
 - *inversion of control + pattern nesting + lower level transformations* → exceptions require a special mechanism.

BLAST Example

```
Skeleton<Blast,File> blast =  
  new DaC<Blast, File>(  
    new ShouldSplit(),  
    new SplitDatabase(),  
    new Pipe<Blast, File>(…),  
    new MergeResults()  
  );
```

*Skeleton
Definition*

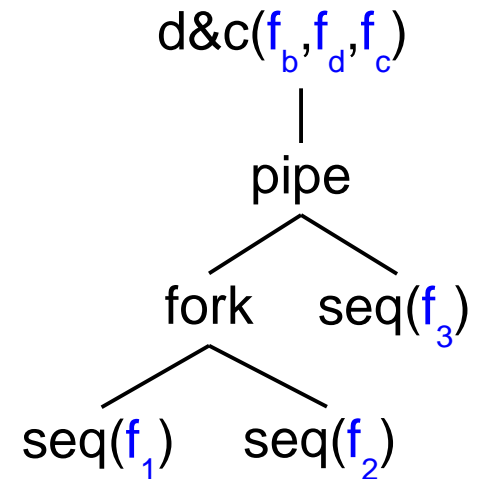
```
Future<File> future =  
  
  blast.input(new Blast(…));
```

Input

```
File result = future.get()
```

Output

BLAST
Skeleton Program



BLAST Example

```
Skeleton<Blast,File> blast =  
  new DaC<Blast, File>(  
    new ShouldSplit(),  
    new SplitDatabase(),  
    new Pipe<Blast, File>(…),  
    new MergeResults()  
  );
```

*Skeleton
Definition*

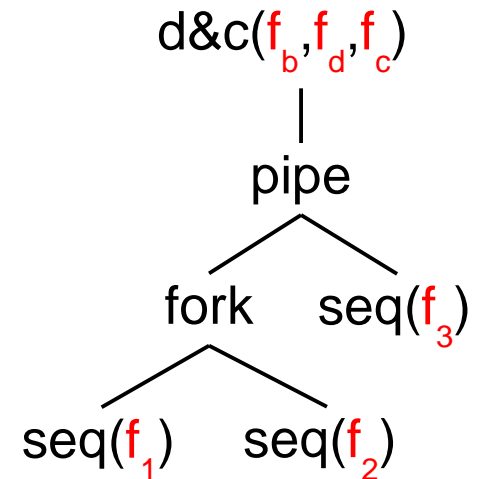
```
Future<File> future =  
  
  blast.input(new Blast(…));
```

Input

```
File result = future.get()
```

Output

BLAST Skeleton Program



 Exception Sources

Muscle Blast Execute (f2)

```
class BlastExecute implements Execute<Blast,File>{  
    command = "/usr/bin/blast";  
  
    public File execute(Blast b) throws IOException {  
  
        Runtime.getRuntime().exec(command + b.args);  
  
        return new File("result.blast");  
    }  
}
```

Exception Model

Alternatives

- **Handle at the current Skeleton Level**

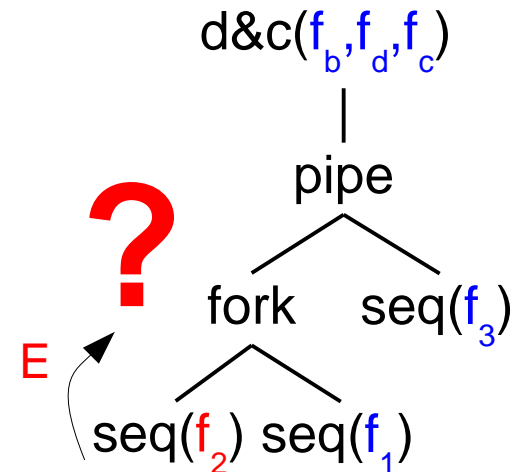
Handler mechanism

- **Report Exception Back to Upper level**

Handlers can be put at any level chosen by the programmer

Return a high-level stack trace to the user if no handler

BLAST Skeleton Program



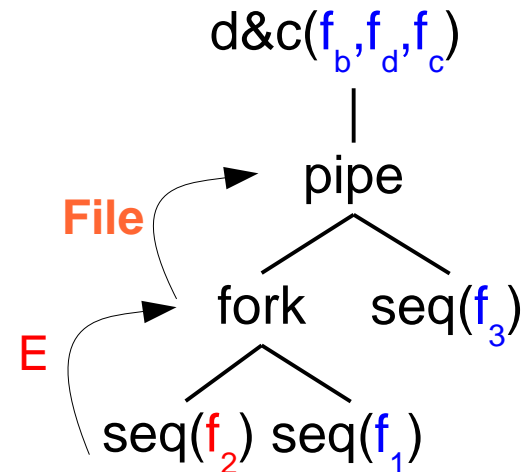
Exception Model

- **Handler**

```
fork = new Fork(....., new IOHandler());
```

```
class IOHandler implements Handler<...>{  
    command = "/usr/bin/blast";  
  
    public File handle(IOException e, Blast b){  
        b = downloadDatabase(b);  
  
        Runtime.(...).exec(command + b.args);  
  
        return new File("result.blast");  
    }  
}
```

BLAST Skeleton Program



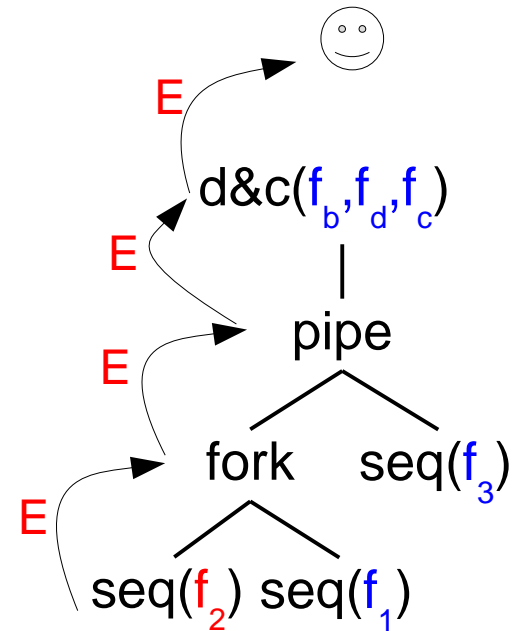
Exception Model

- **Report Exception Back to User**

Exception Stack Trace

```
Caused by: java.lang.Exception: IOException
at examples.blast.BlastExecute.execute(Blast.java:26)
at examples.blast.BlastExecute.execute(Blast.java:1)
at instructions.SeqInst.interpret(SeqInst.java:53)
at system.Interpreter.interLoop(Interpreter.java:69)
at system.Interpreter.inter(Interpreter.java:163)
at system.Task.run(Task.java:137)
```

BLAST Skeleton Program



- Low-level information breaks high-level paradigm!
- **Nested structure information is lost!**

Exception Model

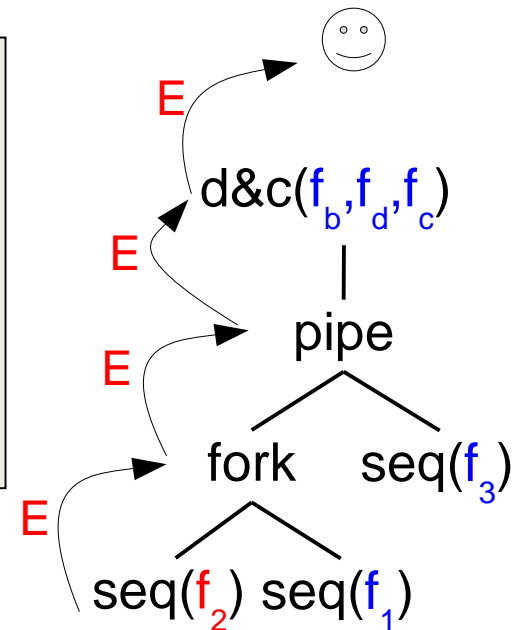
- **Report Exception Back to User**

High-level Stack Trace

Caused by: java.lang.Exception: IOException
at examples.blast.BlastExecute.execute(Blast.java:26)
at examples.blast.BlastExecute.execute(Blast.java:1)
at skeletons.Fork.<init>(Blast.java:68)
at skeletons.Pipe.<init>(Blast.java:53)
at skeletons.DaC.<init>(Blast.java:60)

- Hides low-level information
- **Retraces the skeleton nesting**
- **Exceptions cancel sibling tasks**

BLAST Skeleton Program



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A semantics for algorithmic skeletons

- To precisely and formally **define runtime behaviour**
 - **Small step** semantics for algorithmic skeletons [Leyton's PhD thesis]
 - Here: extend the semantics → define the behaviour of a skeleton with **exceptions** and **handlers**
- To formally prove properties on algorithmic skeletons
 - **Typing algorithmic skeletons** [PDP'08]:
 - Type **preservation** → skeletons can be used to transmit typed values between muscles
 - Type **errors can be detected** statically
 - ... → future works

Illustrative Example

•Skeleton:

$$\Delta = \text{pipe}(if(f_b, seq(f_{pre}, h_p), seq(f_{id})), seq(f_t), h)$$

Translation into instructions (transform code):

$$\begin{aligned} \longrightarrow & \text{pipe}_I(if_I(f_b, seq_I(f_{pre}) \uparrow h_p(\tau_p), seq_I(f_{id}) \uparrow \emptyset(\tau_1)) \\ & \uparrow \emptyset(\tau_i), seq_I(f_t) \uparrow \emptyset(\tau_t)) \uparrow h(\tau) \end{aligned}$$

τ_x = locations of instructions

Why an intermediate language?

- Instead of directly reducing source code
- Better reflect implementation
- Reflect simply task parallelism
- Richer language to express intermediate reduction states
 - e.g. unfold *if*:

$$if_I(f_b, S_{\text{true}}, S_{\text{false}})(p) \rightarrow seq_I(f_b)(p) \cdot choice(p, S_{\text{true}}, S_{\text{false}})$$

Notations:

Handler

● Sequence

| Parallelism

Illustrative Example

Provide input: d_1

$$\begin{aligned} & pipe_I(if_I(f_b, seq_I(f_{pre}) \uparrow h_p(\tau_p), seq_I(f_{id}) \uparrow \emptyset(\tau_1)) \\ & \quad \uparrow \emptyset(\tau_i), seq_I(f_t) \uparrow \emptyset(\tau_t)) \uparrow h(\tau)([d_1]) \end{aligned}$$

Illustrative Example

Remember data

$$\begin{aligned} & pipe_I(if_I(f_b, seq_I(f_{pre}) \uparrow h_p(\tau_p), seq_I(f_{id}) \uparrow \emptyset(\tau_1)) \\ & \quad \uparrow \emptyset(\tau_i), seq_I(f_t) \uparrow \emptyset(\tau_t))(d_1) \uparrow h(\tau, d_1) \end{aligned}$$

Illustrative Example

Pipe reduction

$$if_I(f_b, seq_I(f_{pre}) \uparrow h_p(\tau_p), seq_I(f_{id}) \uparrow \emptyset(\tau_1)) \\ \uparrow \emptyset(\tau_i)(d_1) \odot pipe_I(seq_I(f_t) \uparrow \emptyset(\tau_t)) \uparrow h(\tau, d_1)$$

Illustrative Example

Remember data+ if unfolding

$$\begin{aligned} & seq_I(f_b)(d_1) \cdot choice_I(d_1, seq_I(f_{pre}) \uparrow h_p(\tau_p), seq_I(f_{id}) \uparrow \emptyset(\tau_1)) \\ & \uparrow \emptyset(\tau_i, d_1) \cdot pipe_I(seq_I(f_t) \uparrow \emptyset(\tau_t)) \uparrow h(\tau, d_1) \end{aligned}$$

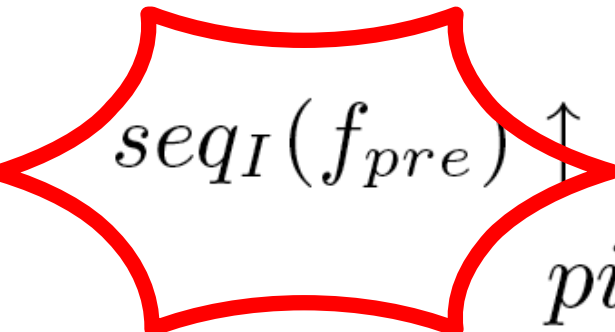
Illustrative Example

Sequential reduction:

$$\begin{aligned} & \text{true} \cdot \text{choice}_I(d_1, \text{seq}_I(f_{pre})) \uparrow h_p(\tau_p), \text{seq}_I(f_{id}) \uparrow \emptyset(\tau_1)) \\ & \uparrow \emptyset(\tau_i, d_1) \cdot \text{pipe}_I(\text{seq}_I(f_t) \uparrow \emptyset(\tau_t)) \uparrow h(\tau, d_1) \end{aligned}$$

Illustrative Example

choice:


$$seq_I(f_{pre}) \uparrow h_p(\tau_p)(d_1) \uparrow \emptyset(\tau_i, d_1) \cdot$$

$$pipe_I(seq_I(f_t) \uparrow \emptyset(\tau_t)) \uparrow h(\tau, d_1)$$

Illustrative Example

Exception e raised:

$$e \uparrow h_p(\tau_p, d_1) \uparrow \emptyset(\tau_i, d_1) \cdot \text{pipe}_I(\text{seq}_I(f_t) \uparrow \emptyset(\tau_t)) \uparrow h(\tau, d_1)$$

Illustrative Example

Uncaught exception \rightarrow trace remembered

$$\tau_i \oplus \tau_p \oplus e \cdot pipe_I(seq_I(f_t) \uparrow \emptyset(\tau_t)) \uparrow h(\tau, d_1)$$

Illustrative Example

Lookup in the next handler

$$\tau_i \oplus \tau_p \oplus e \uparrow h(\tau, d_1)$$

Illustrative Example

Exception caught

$$h(d_1, \tau_i \oplus \tau_p \oplus e)$$

Conclusion

- Theoretical (semantics+proofs) and practical (Java library)
- Typing algorithmic skeletons
 - No further type casts inside muscles
 - Type errors detected at skeleton composition
 - Skeletons transfer types between muscles
- Exceptions for Algorithmic Skeletons:
 - Featuring Support for
 - Asynchronous computations
 - Parallel Patterns Nesting
 - High level stack trace
 - Provide high-level stack trace back to users

Thank you