

A new bridging model for high-performance programming

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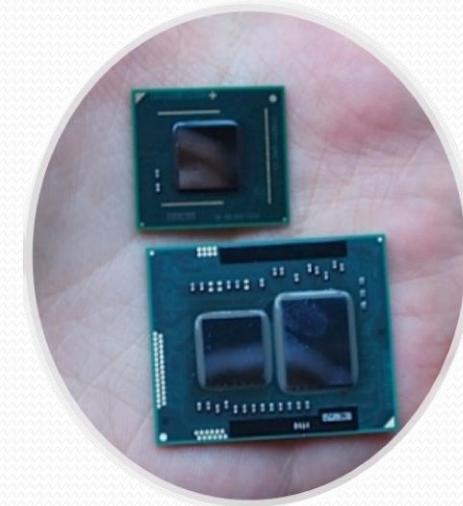
PLAN

- Bridging Models
- Scatter-Gather Language
- Operational Semantics

Parallel Computing & Bridging Model

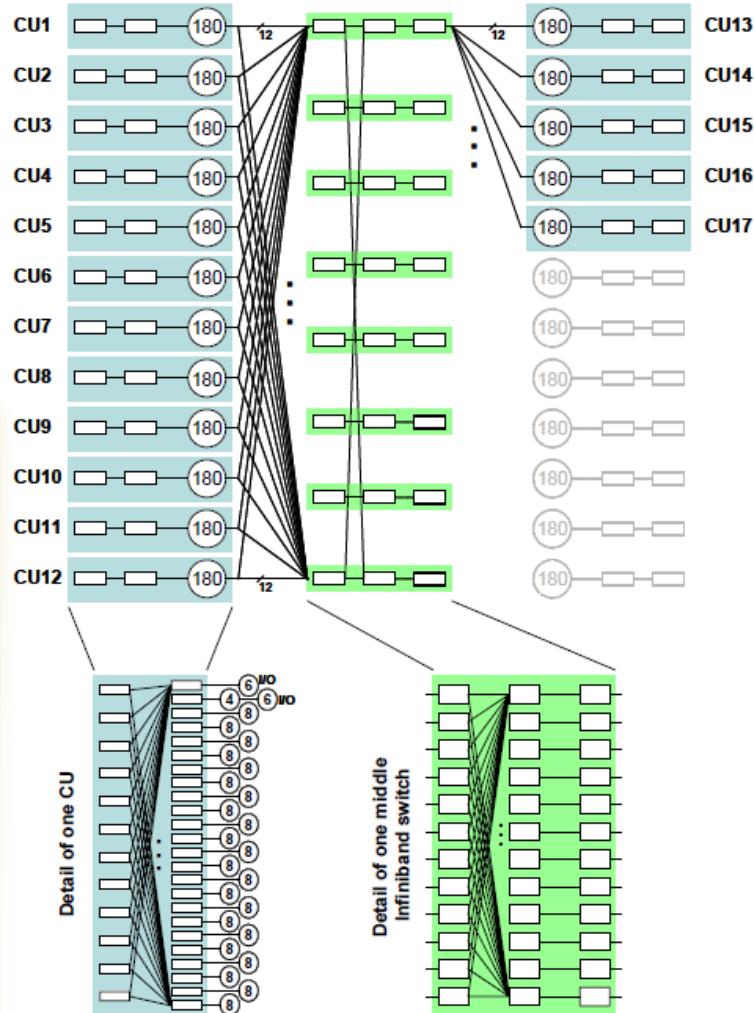
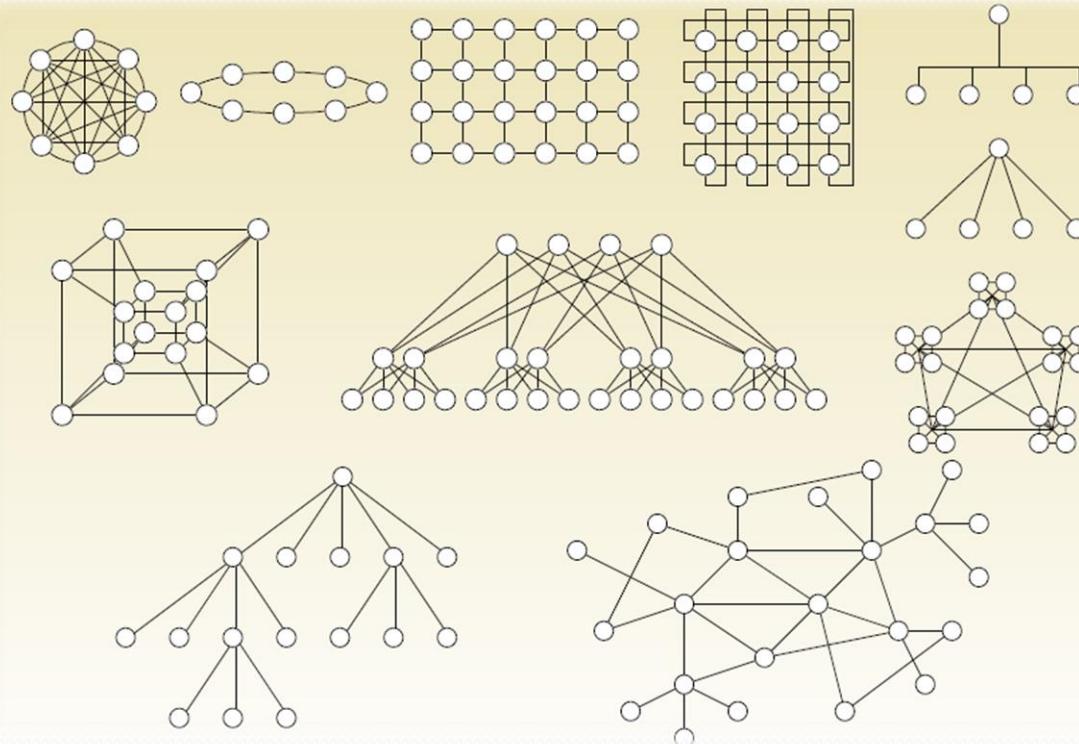
Various Computers

- Multi-core computing
 - e.g. Intel i5, STI cell
- Symmetric multiprocessing (SMP)
 - iden proc, share memory, connect via a bus*
- Specialized parallel computers
 - FPGA
 - GP-GPU
 - ASIC
 - Vector processors
- Distributed computing
 - Cluster computing
 - Massive parallel processing (MPP) \approx big cluster
 - Grid computing



distributed form, over Internet

Various Topologies



- An overview of the Roadrunner system interconnection

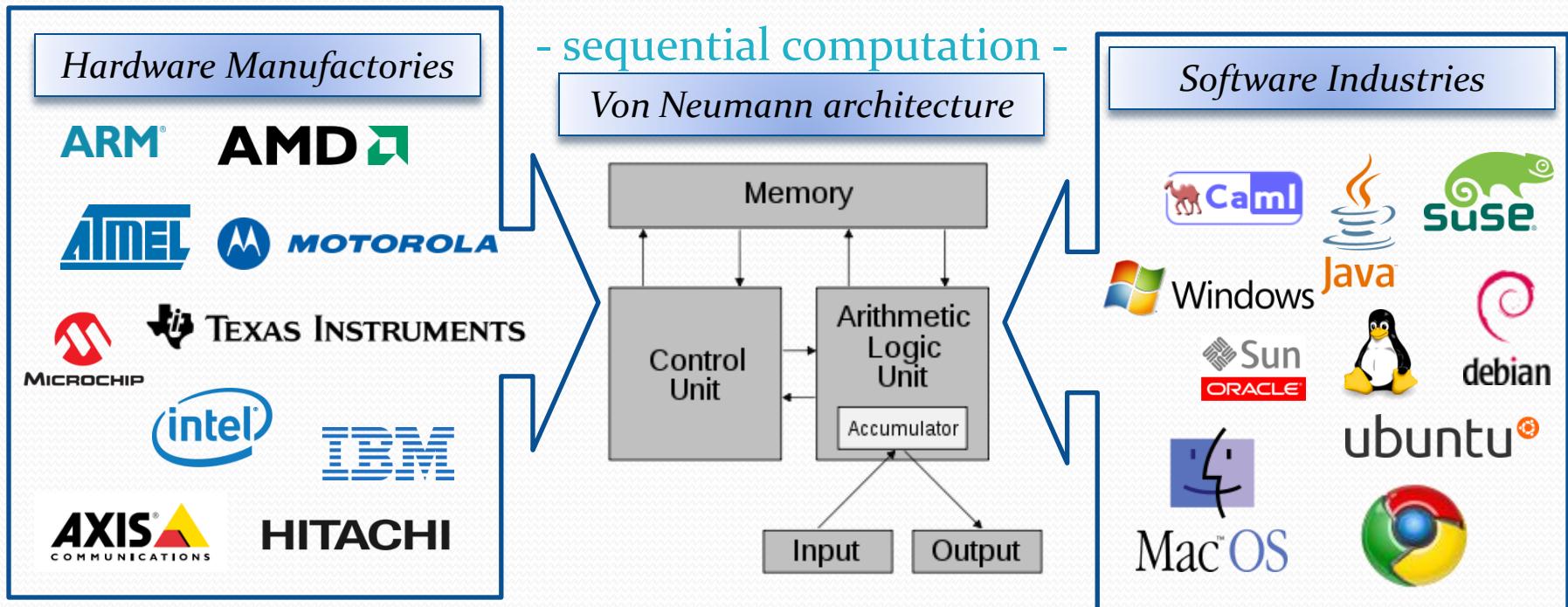
Top 500 (November 2010)

Rank	Rmax Rpeak (Tflops)	Name	Computer Processor cores	Vendor	Site Country, Year
1	2566.00 4701.00	Tianhe-1A	NUDT YH Cluster 14,336x6 Xeon + 7168×14 Fermi, Proprietary	NUDT	National Supercomputing Center in Tianjin China, 2010
2	1759.00 2331.00	Jaguar	Cray XT5 224,162 Opteron	Cray	Oak Ridge National Laboratory United States, 2009
3	1271.00 2984.30	Nebulae	Dawning TC3600 Blade 55,680 Xeon + 64,960 Tesla, InfiniBand	Dawning	National Supercomputing Center in Shenzhen (NSCS) China, 2010
4	1192.00 2287.63	TSUBAME 2.0	HP Cluster Platform 3000SL 73,278 Xeon, Fermi	NEC/HP	GSIC Center, Tokyo Institute of Technology Japan, 2010
5	1054.00 1288.63	Hopper	Cray XE6 153,408 Opteron	Cray	DOE/SC/LBNL/NERSC United States, 2010
6	1050.00 1254.55	Tera 100	Bull Bullx 138,368 Xeon, InfiniBand	Bull SA	Commissariat à l'énergie atomique (CEA) France, 2010
7	1042.00 1375.78	Roadrunner	BladeCenter QS22/LS21 122,400 Cell/Opteron	IBM	Los Alamos National Laboratory United States, 2009
8	831.70 1028.85	Kraken	Cray XT5 98,928 Opteron	Cray	National Institute for Computational Sciences United States, 2009
9	825.50 1002.70	JUGENE	Blue Gene/P Solution 294,912 Power	IBM	Forschungszentrum Jülich Germany, 2009
10	816.60 1028.66	Cielo	Cray XE6 107,152 Opteron	Cray	DOE/NNSA/LANL/SNL United States, 2010

Bridging Model for Computation

- The success of the von Neumann model of sequential computation is attributable to the fact that it is an efficient bridge between software and hardware: high-level languages can be efficiently compiled on to this model; yet it can be efficiently implemented in hardware.

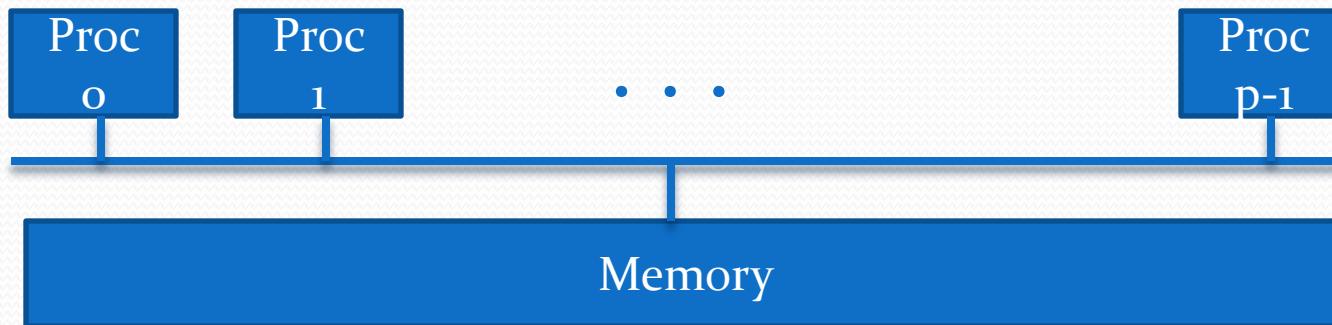
-- Leslie G. Valiant, 1990



PRAM Model

PRAM: Parallel Random-Access Machine (*Fortune et Wyllie, 1978*)

- *Shared-memory (random memory access)*
- *Synchronized-processor (same μ Proc clock)*

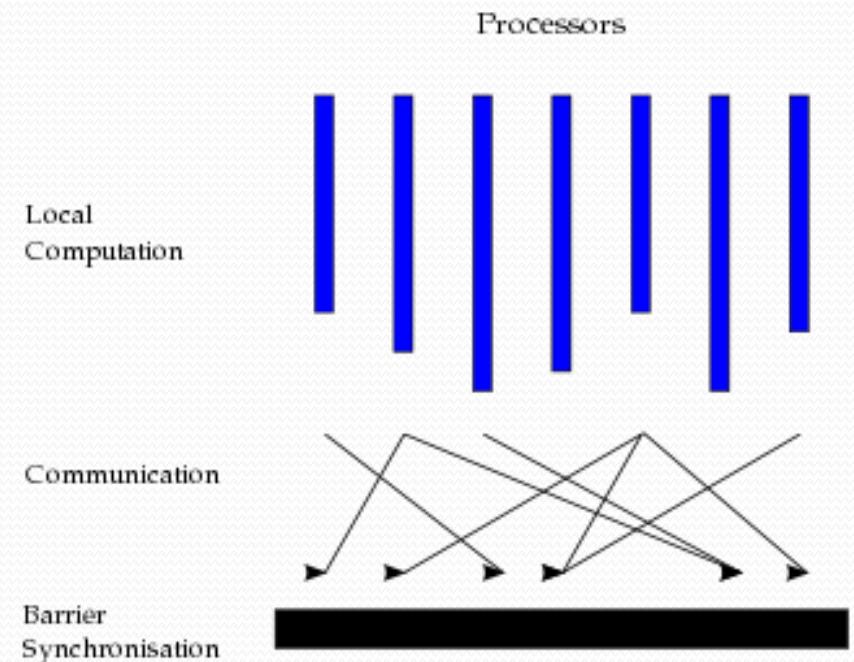
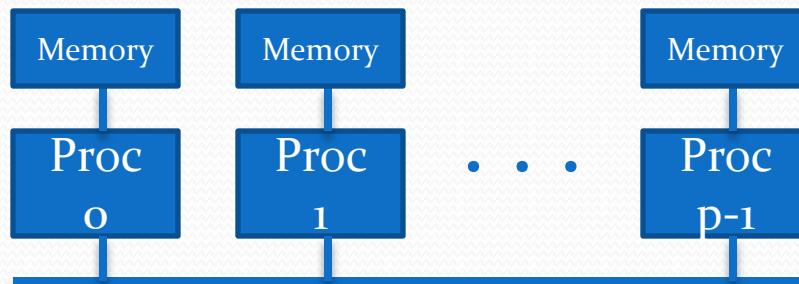


- Exclusive Read, Exclusive Write (EREW) PRAM
- Concurrent Read, Exclusive Write (CREW) PRAM
- Exclusive Read, Concurrent Write (ERCW) PRAM
- Concurrent Read, Concurrent Write (CRCW) PRAM

BSP Model

- **BSP: Bulk-Synchronous Parallel** (*Valiant, Aug 1990*)

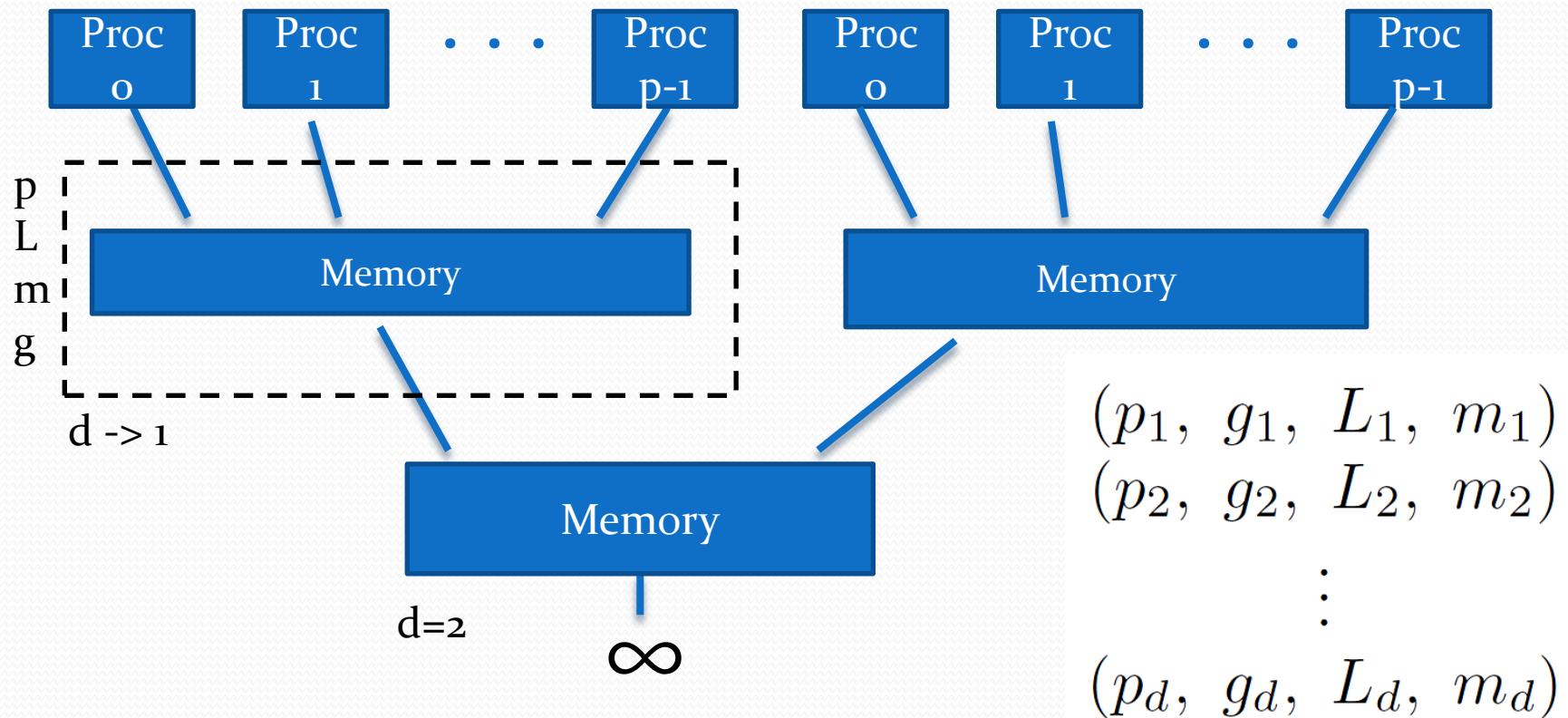
- Processor-memory pair
- Synchronization barrier



$$W + Hg + Sl = \sum_{s=1}^S w_s + g \sum_{s=1}^S h_s + Sl$$

Multi-BSP Model

- A bridging model for multi-core computing (*Valiant, 2008*)

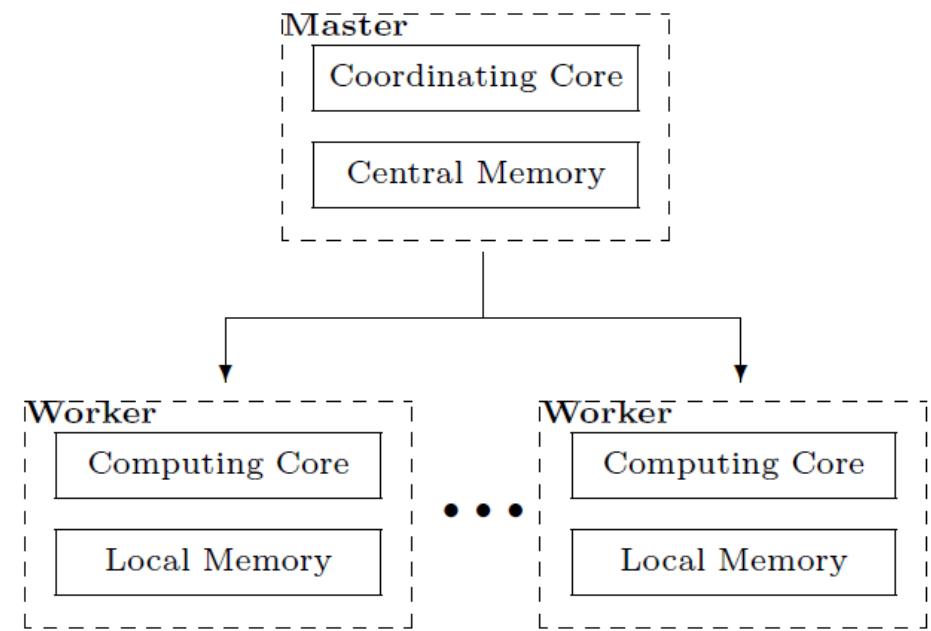
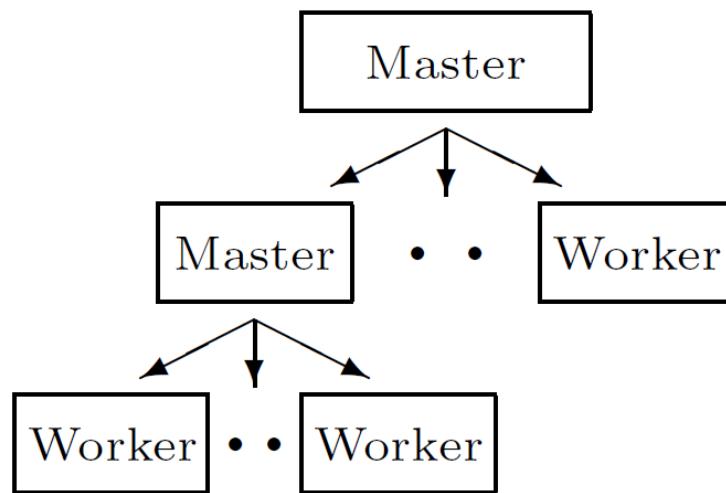


Scatter-Gather Language

Objectives

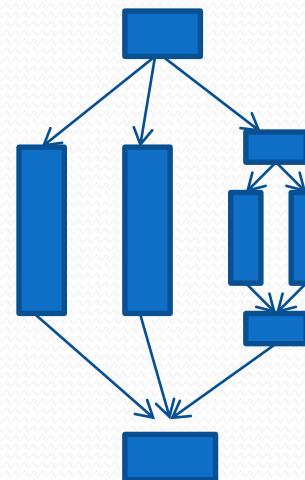
- Easy to learn, easy to use
- Portability of programmes
- Support heterogeneous machine
- Support hybrid architecture
- Performance prediction

Abstract Machine



Execution Model

- A program is composed of a sequence of *supersteps*
- A *superstep* is composed of 4 phases:
 - Scatter communication phase
 - Children computation phase
 - A child computation phase can also be sub-*superstep*
 - Gather communication phase
 - Master computation phase



Cost Model

- l : latency of *scatter* or *gather*
- g : gap, minimum time interval for transmitting one word
- k : number of words to transmit
- w : works to be performed
- c : computation speed of processor
- p : number of children

$$Supstep_{par} = 2l + k_{\downarrow} * g_{\downarrow} + \max_{i=1..p} (Supstep_{children}) + k_{\uparrow} * g_{\uparrow} + w * c$$

$$Supstep_{seq} = w * c$$

Programming Model

- Operational Semantics
 - Syntax
 - Evaluations
 - Examples

Syntax

- **Values**

- $n \in$ numbers **Nat**
- $\langle n_1, n_2, \dots n_\ell \rangle \in$ arrays of number **Vec**
- $\langle v_1, v_2, \dots v_\ell \rangle \in$ arrays of array **VecVec**

- **Locations**

- $X \in$ scalar locations **NatLoc**
Here X or $X_0 \Rightarrow Master$, $X_{i=1..p} \Rightarrow Child$
- $\vec{V} \in$ vectorial locations **VecLoc**
Here \vec{V} or $\vec{V}_0 \Rightarrow Master$, $\vec{V}_{i=1..p} \Rightarrow Child$
- $\widetilde{W} \in$ vectorial vectorial locations **VVecLoc**

Syntax (cont.)

- Operations

- $\odot \in$ binary operations $\mathbf{Op} ::= + \mid - \mid * \mid /$

- Expressions

- $a \in$ scalar arithmetic expressions $\mathbf{Aexp} ::= n \mid X \mid a \odot a \mid \vec{V}[a]$
- $b \in$ scalar boolean expressions $\mathbf{Bexp} ::= \mathbf{true} \mid \mathbf{false} \mid a = a \mid a \leq a \mid \neg b \mid b \wedge b \mid b \vee b$
- $v \in$ vectorial expressions $\mathbf{Vexp} ::= \langle a_1, a_2, \dots, a_\ell \rangle \mid \vec{V} \mid v \odot a \mid v \odot v \mid \widetilde{W}[a]$
- $w \in$ vectorial vectorial expressions $\mathbf{VVexp} ::= \langle v_1, v_2, \dots, v_\ell \rangle \mid \widetilde{W}$

Syntax (cont.)

- Commands
 - $c \in$ primitive commands **Com** ::=
 $X := a \mid \vec{V} := v \mid \widetilde{W} := w \mid c ; c$
| skip | if b then c else c | for X from a to a do c
| scatter w to \vec{V} | scatter v to X
| gather \vec{V} to \widetilde{W} | gather X to \vec{V}
| pardo c
 - Auxiliary commands **Aux** ::=
numChd | len \vec{V} | len \widetilde{W}

Evaluations

- State/Environment Functions

- $\sigma : NatLoc \rightarrow Nat$, thus $\sigma(X) \in Nat$
- $\sigma : VecLoc \rightarrow Vec$, thus $\sigma(\vec{V}) \in Ver$
- $\sigma : VVecLoc \rightarrow VecVec$, thus $\sigma(\widetilde{W}) \in VecVec$

Here $Pos \in Nat$ denotes a position of location:

$0 \Rightarrow master$ (same as above), and $i \in \{1..p\} \Rightarrow i$ -th child.

- $\sigma : NatLoc \rightarrow Pos \rightarrow Nat$, thus $\sigma(X_{pos}) = \sigma_{pos}(X) \in Nat$
- $\sigma : VecLoc \rightarrow Pos \rightarrow Vec$, thus $\sigma(\vec{V}_{pos}) = \sigma_{pos}(\vec{V}) \in Vec$

Evaluations (cont.)

- Primitive Commands

- Scatters

$$\frac{\langle w, \sigma \rangle \rightarrow < v_1, v_2, \dots, v_\ell > \quad \forall_{i=1..numChd} \langle \vec{V}_i := v_i, \sigma \rangle \rightarrow \sigma'_i}{\langle \text{scatter } w \text{ to } \vec{V}, \sigma \rangle \rightarrow \sigma'}$$

$$\frac{\langle v, \sigma \rangle \rightarrow < n_1, n_2, \dots, n_\ell > \quad \forall_{i=1..numChd} \langle X_i := n_i, \sigma \rangle \rightarrow \sigma'_i}{\langle \text{scatter } v \text{ to } X, \sigma \rangle \rightarrow \sigma'}$$

- Gathers

$$\frac{\langle \widetilde{W} := < \vec{V}_1, \vec{V}_2, \dots, \vec{V}_{numChd} >, \sigma \rangle \rightarrow \sigma'}{\langle \text{gather } \vec{V} \text{ to } \widetilde{W}, \sigma \rangle \rightarrow \sigma'}$$

$$\frac{\langle \vec{V} := < X_1, X_2, \dots, X_{numChd} >, \sigma \rangle \rightarrow \sigma'}{\langle \text{gather } X \text{ to } \vec{V}, \sigma \rangle \rightarrow \sigma'}$$

- Parallel

$$\frac{\forall_{i=1..chdnum} \langle c, \sigma_i \rangle \rightarrow \sigma'_i}{\langle \text{parдо } c, \sigma \rangle \rightarrow \sigma'}$$

Example

- Sum

Algorithm 1 Procedure: Sum(in Vec, out Nat)

```
if ( $numChd \neq 0$ ) and (use children) then
     $\widetilde{W} :=$  cut  $\overrightarrow{Src}$  to suit for children
    scatter  $\widetilde{W}$  to  $\overrightarrow{V}$ 
    for all par do
         $Sum(\overrightarrow{V}, LocRes)$ 
    end for
    gather  $LocRes$  to  $\overrightarrow{Res}$ 
    if parallel needed then
         $Sum(\overrightarrow{Res}, Result)$ 
    else
         $Result := \sum \overrightarrow{Res}$ 
    end if
    else
         $Result := \sum \overrightarrow{Src}$ 
    end if
    return  $Result$ 
```

$$\begin{aligned} Supstep_{par} &= 2l + (k_{in} + p) * g + \max_{i=1..p} (Supstep_{children}) + O(sum(p)) * c \\ Supstep_{seq} &= O(sum(k_{in})) * c \end{aligned}$$

Example - Sort

Algorithm 2 Procedure: Sort(in V, out V)

```
if ( $numChd \neq 0$ ) and (use children) then
     $\widetilde{W}$  := cut  $\overrightarrow{Src}$  to suit for children
    scatter  $\widetilde{W}$  to  $\overrightarrow{V}$ 
    for all do
         $Sort(\overrightarrow{V}, \overrightarrow{V}')$ 
    end for
    gather  $\overrightarrow{V}'$  to  $\widetilde{List}$ 
     $\overrightarrow{Res}$  := merge  $\widetilde{List}$ 
else
     $\overrightarrow{Res}$  := sort  $\overrightarrow{Src}$ 
end if
return  $\overrightarrow{Res}$ 
```

$$Supstep_{par} = 2l + (2 * k) * g + \max_{i=1..p} (Supstep_{children}) + O(merge(k)) * c$$

$$Supstep_{seq} = O(sort(k)) * c$$

Example - Scan

Algorithm 3 Procedure: Scan(in V , out V)

```
if ( $numChd \neq 0$ ) and (use children) then
     $\widetilde{W} :=$  cut  $\overrightarrow{Src}$  to suit for children
    scatter  $\widetilde{W}$  to  $\overrightarrow{V}$ 
    for all do
         $Scan(\overrightarrow{V}, \overrightarrow{V}')$ 
         $X := \overrightarrow{V}'[\text{len } \overrightarrow{V}']$ 
    end for
    gather  $X$  to  $\overrightarrow{Lst}$ 
    for  $i$  from 2 to ( $\text{len } \overrightarrow{Lst}$ ) do  $\overrightarrow{Lst}[i] := \overrightarrow{Lst}[i - 1]$ 
     $\overrightarrow{Lst}[1] := 0$ 
     $\overrightarrow{Lst} := \text{scan } \overrightarrow{Lst}$ 
    scatter  $\overrightarrow{Lst}$  to  $X$ 
    for all do
         $\overrightarrow{V}' := \overrightarrow{V}' + X$ 
    end for
    gather  $\overrightarrow{V}'$  to  $\widetilde{W}$ 
     $\overrightarrow{Res} := \text{concatenate } \widetilde{W}$ 
else
     $\overrightarrow{Res} := \text{scan } \overrightarrow{Src}$ 
end if
return  $\overrightarrow{Res}$ 
```

Future works

- Implementation
- Experiments
- Optimization
 - Communication between children
 - Pipeline
 - ...
- Load Balancing
- New Algorithms
- ...

Thank you for your time

- Questions?

